

AUTOMATIC DELTATAU PROJECT AND CODE GENERATION FOR GRANITE BENCHES AT SIRIUS

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T. R. S. Soares
J. V. E. Matoso
J. P. S. Furtado

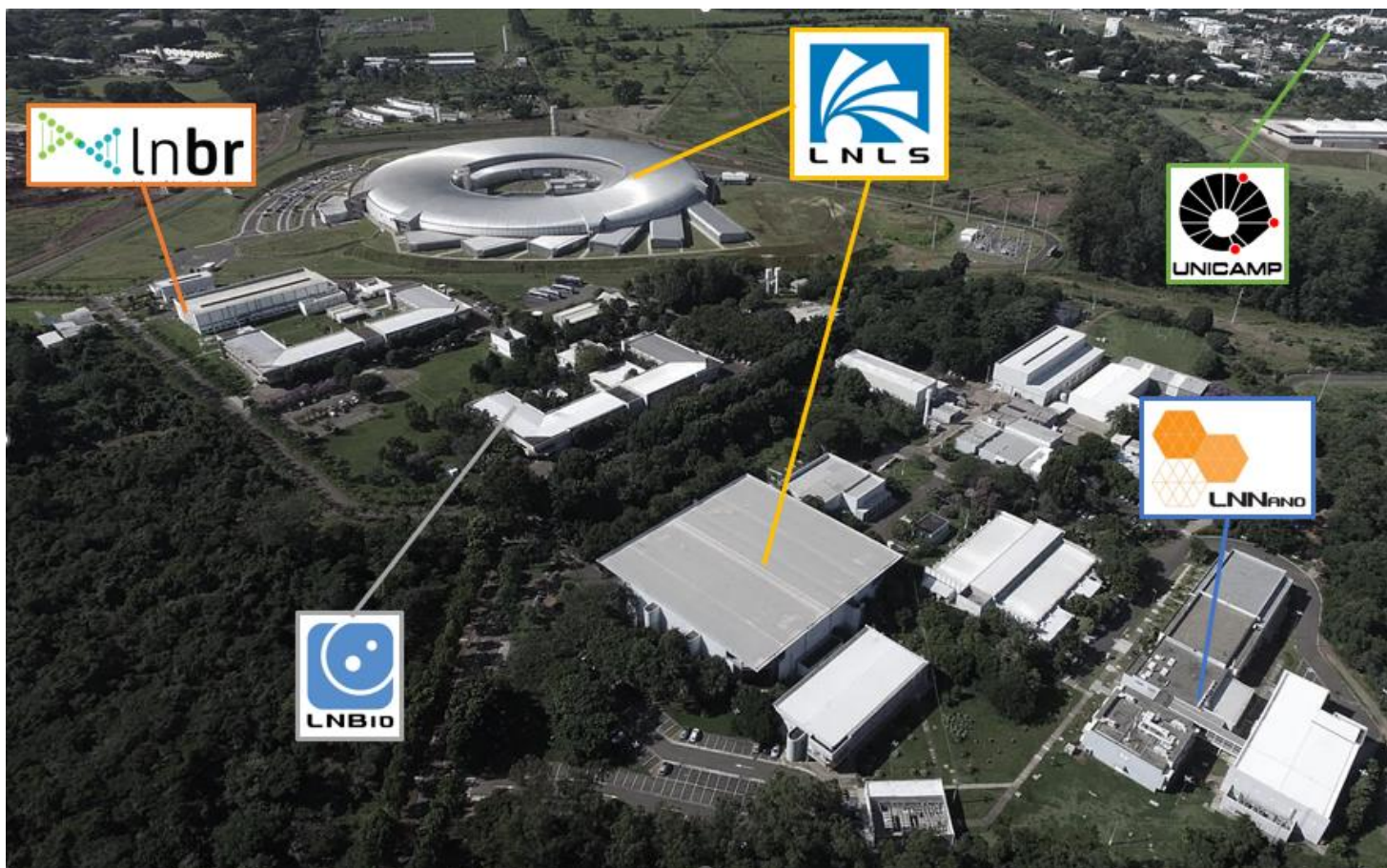
Brazilian Synchrotron Light Laboratory (LNLS), Brazil.

telles.soares@lnls.br
joao.matoso@lnls.br

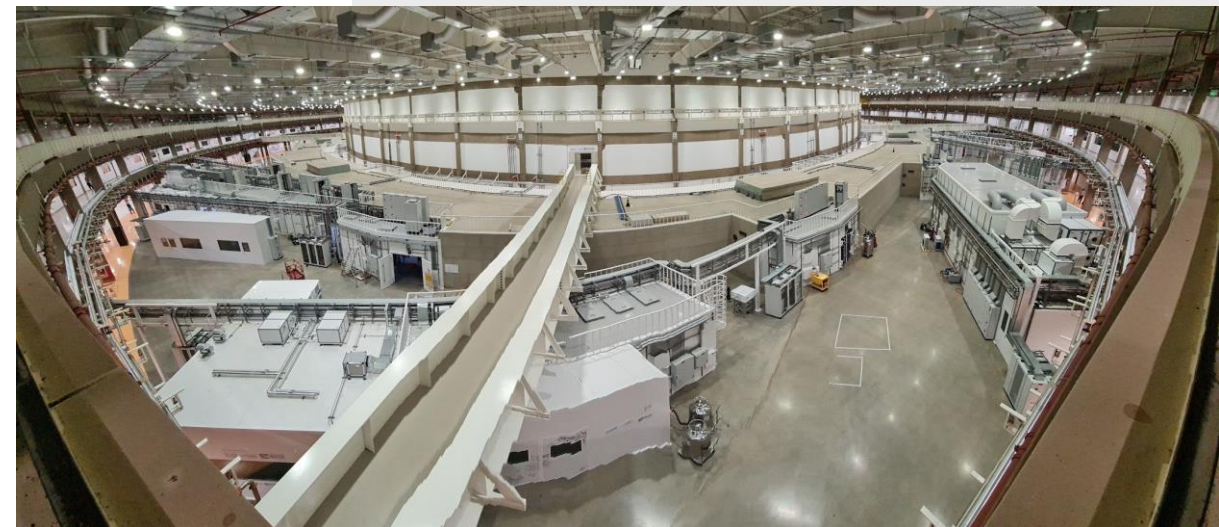


Introduction

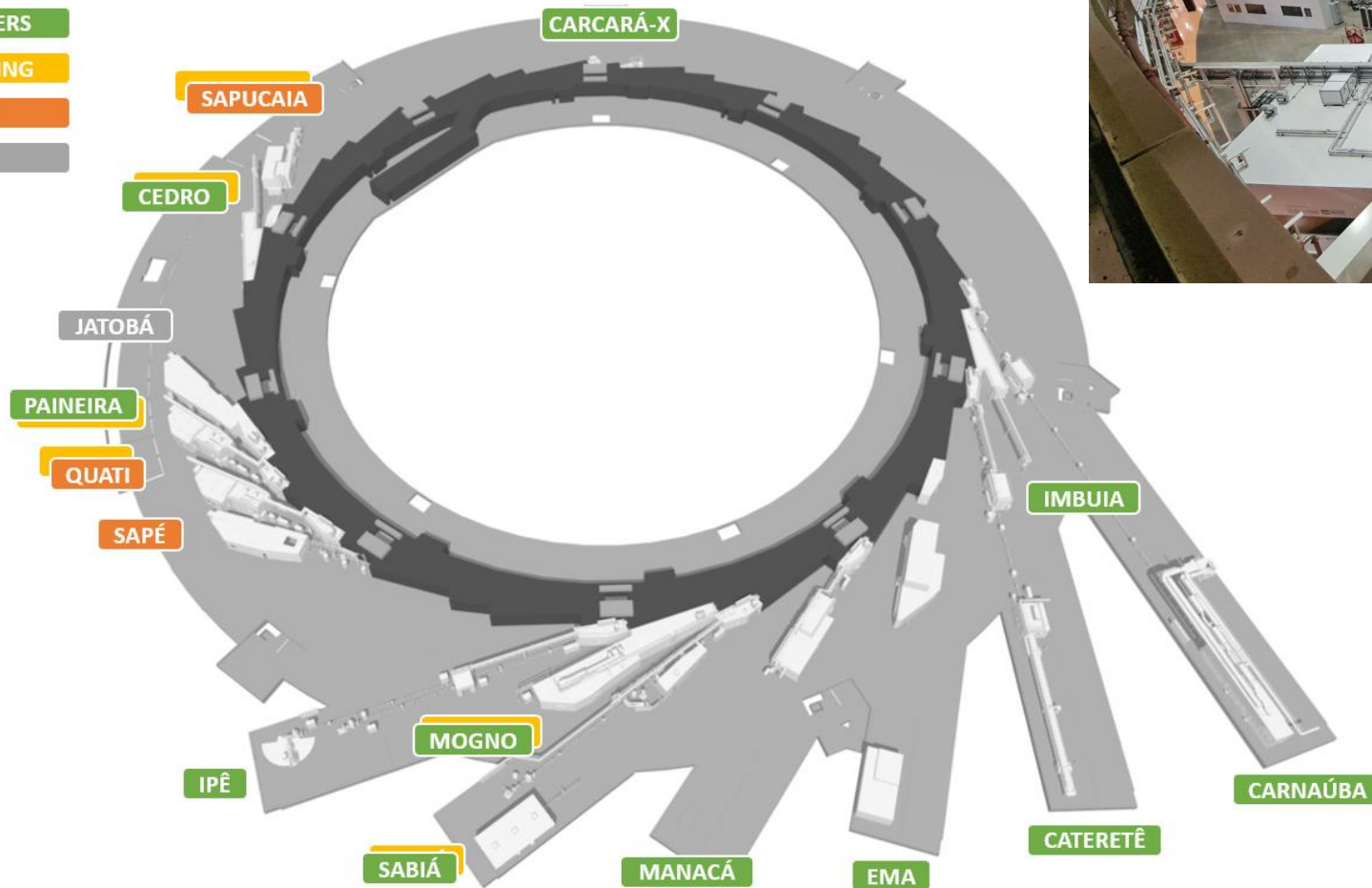
- LNLS – Brazilian Synchrotron Light Source
- Sirius - 4th generation storage ring



Sirius Status – Phase 1

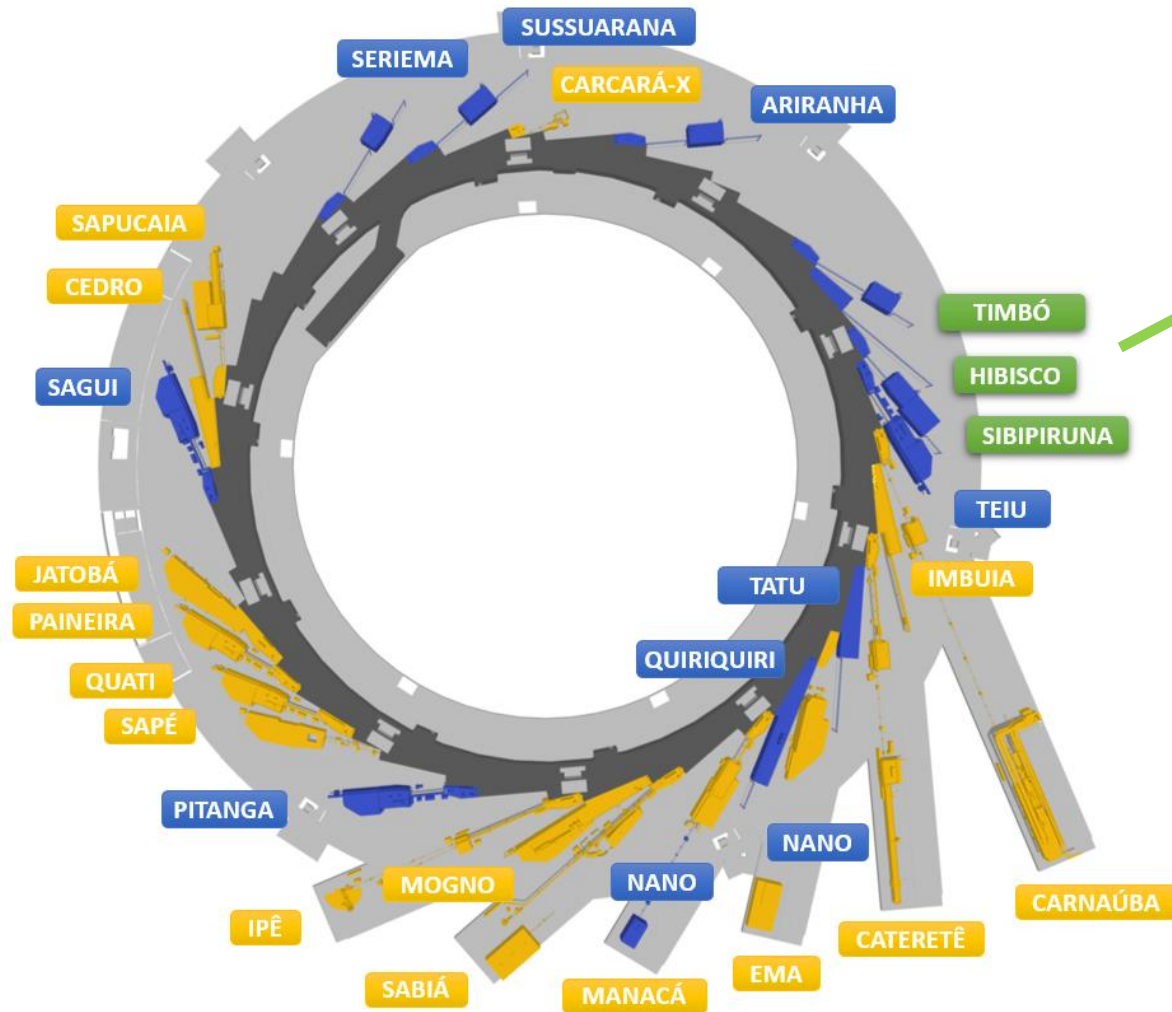


- EXTERNAL USERS
- COMMISSIONING
- ASSEMBLY
- DESIGN



Sirius Status

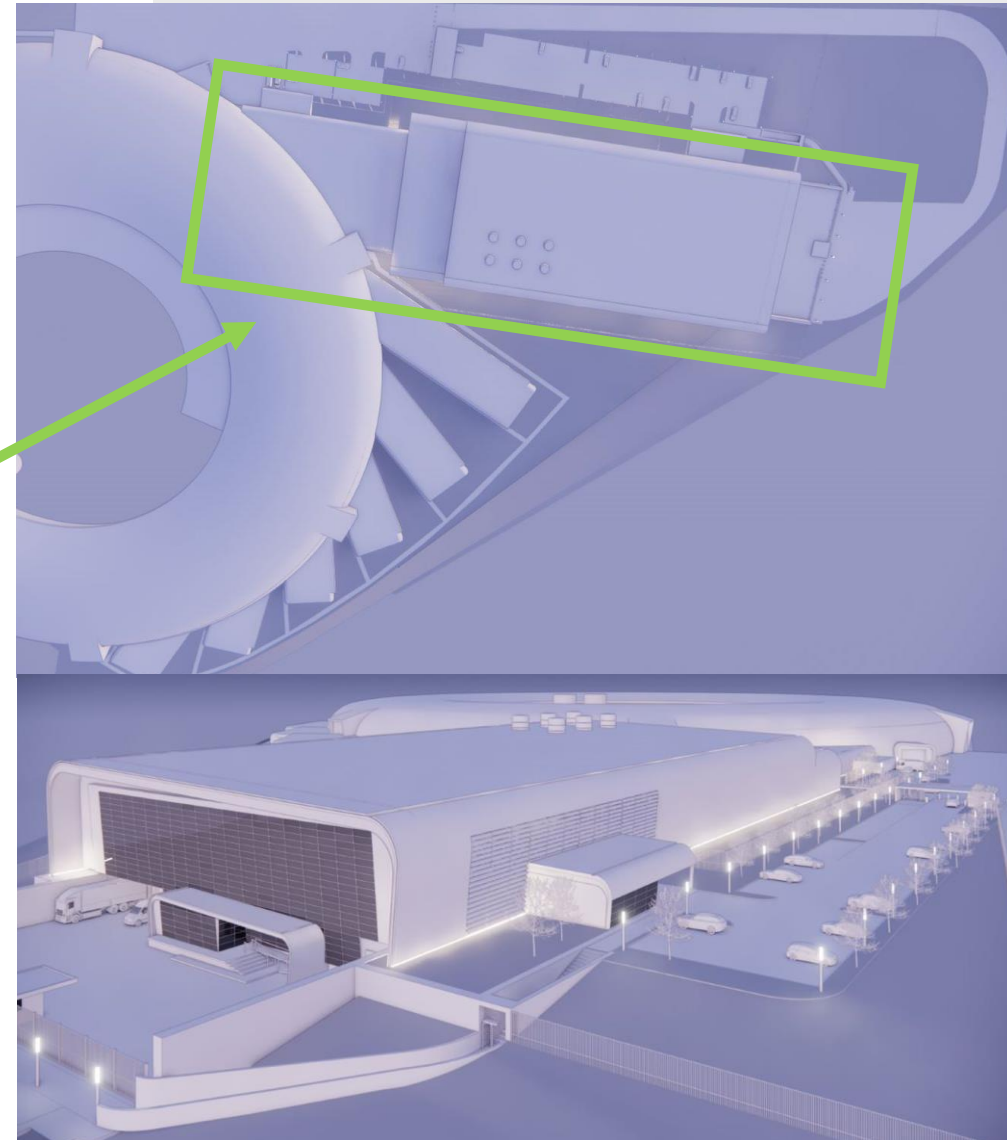
- PHASE I
- PHASE II
- ORION



Orion (NB4)

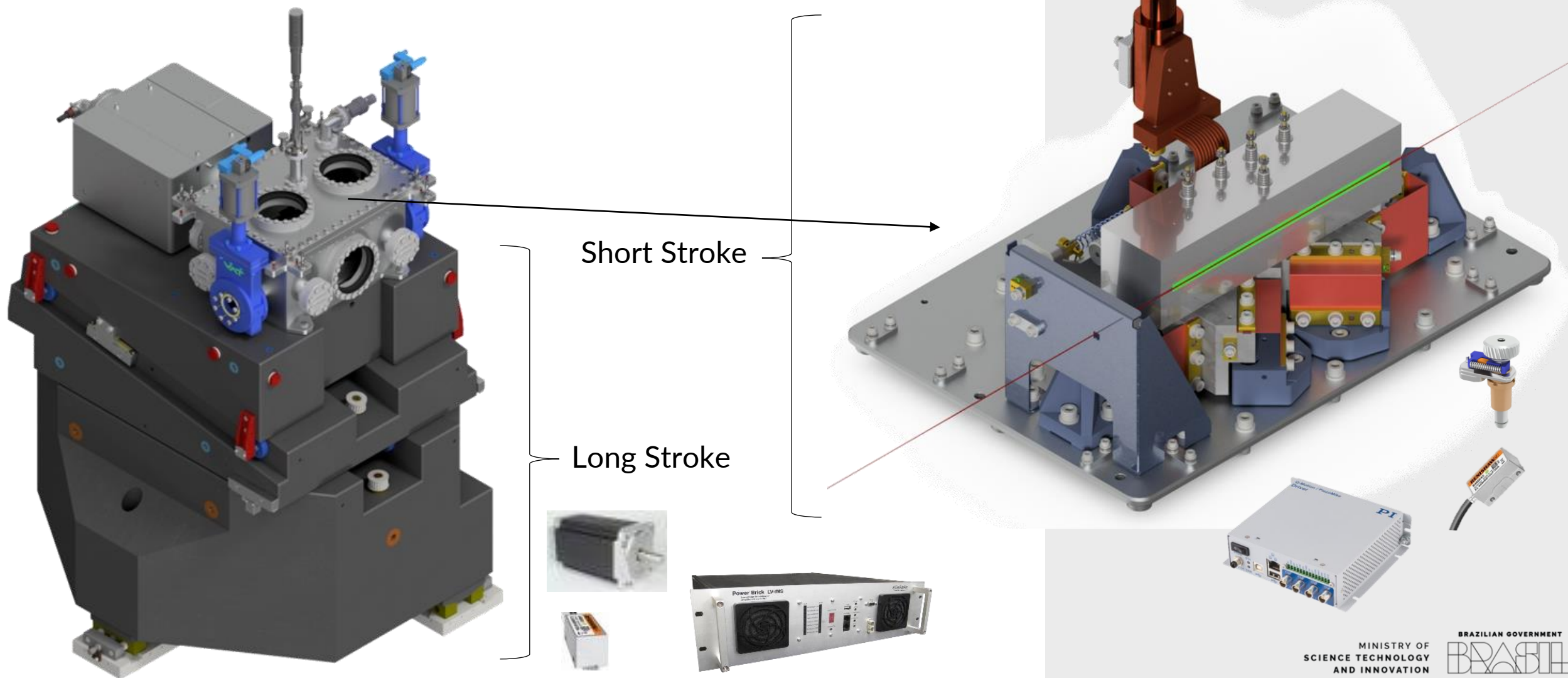


CNPEM



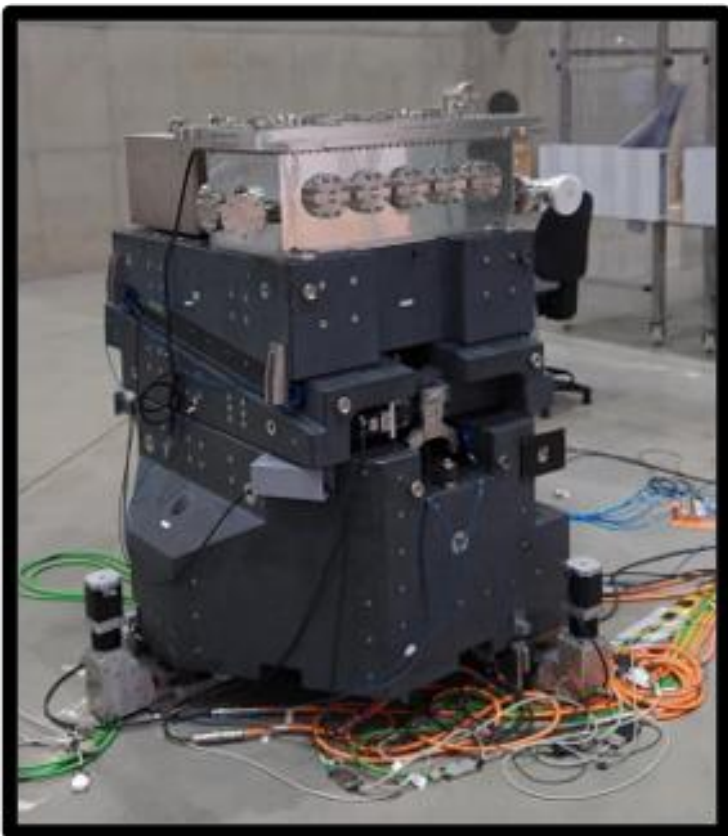
Granite Bench Overview

- High coupling stiffness to the ground and position control



Granite Bench Implementation

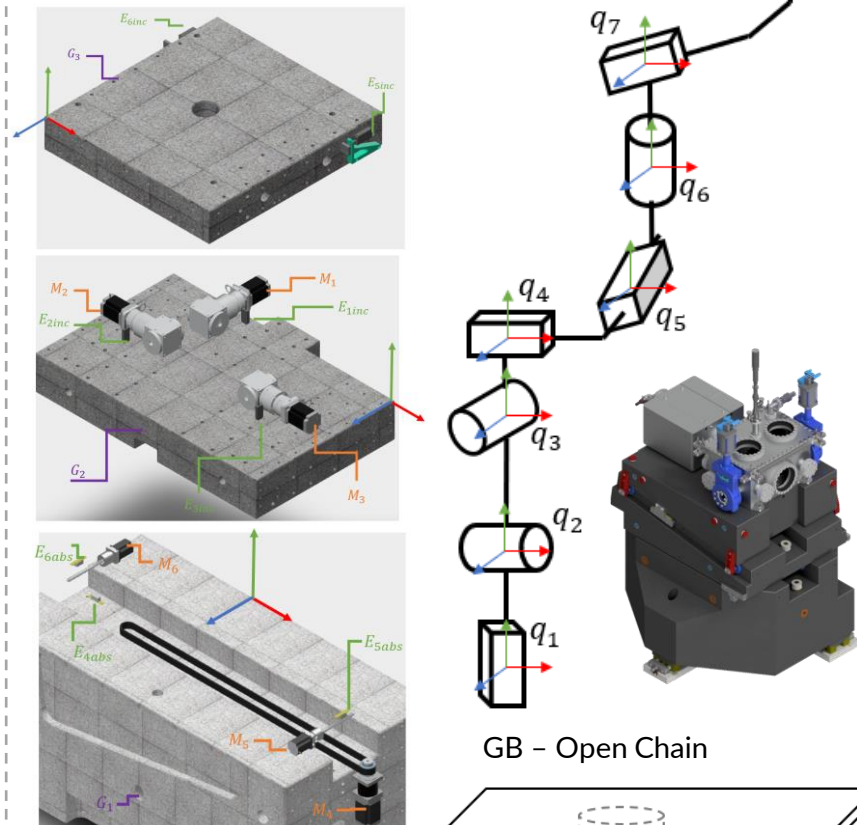
Assembly validation



Granite bench (GB)
 4 stepper motors with abs. feedback
 Air-bearing system for movement
Levelers - Tripod
 3 stepper motors with inc. feedback



Kinematics Modeling



GB - Open Chain

Levelers - Closed Chain

Numerical Method to solve Kinematics Equations

$$e_i = \begin{bmatrix} T_{y',i} \\ \theta_{x',i} \\ \theta_{z',i} \end{bmatrix} \quad J(e_i) = \begin{bmatrix} \frac{\partial p_1}{\partial T_{y'}}(e_i) & \frac{\partial p_1}{\partial \theta_{x'}}(e_i) & \frac{\partial p_1}{\partial \theta_{z'}}(e_i) \\ \frac{\partial p_2}{\partial T_{y'}}(e_i) & \frac{\partial p_2}{\partial \theta_{x'}}(e_i) & \frac{\partial p_2}{\partial \theta_{z'}}(e_i) \\ \frac{\partial p_3}{\partial T_{y'}}(e_i) & \frac{\partial p_3}{\partial \theta_{x'}}(e_i) & \frac{\partial p_3}{\partial \theta_{z'}}(e_i) \end{bmatrix}$$

Iteration Vector

Jacobian Matrix

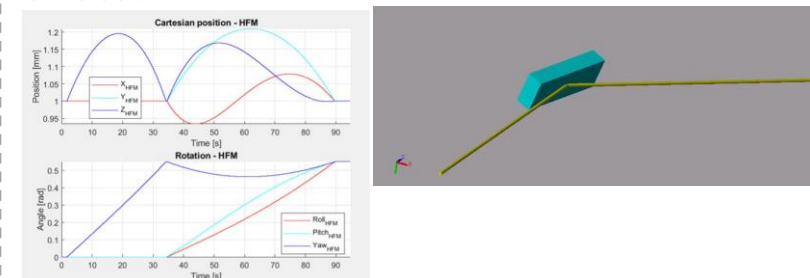
$$G(p_{1,raw}, p_{2,raw}, p_{3,raw}) = \begin{bmatrix} p_{1,raw} - p_1(e_i) \\ p_{2,raw} - p_2(e_i) \\ p_{3,raw} - p_3(e_i) \end{bmatrix}$$

Minimization Vector

$$e_{i+1} = e_i + J^{-1}(e_i)G(p_{raw}, e_i)$$

Iteration Algorithm

Simulation



C Code



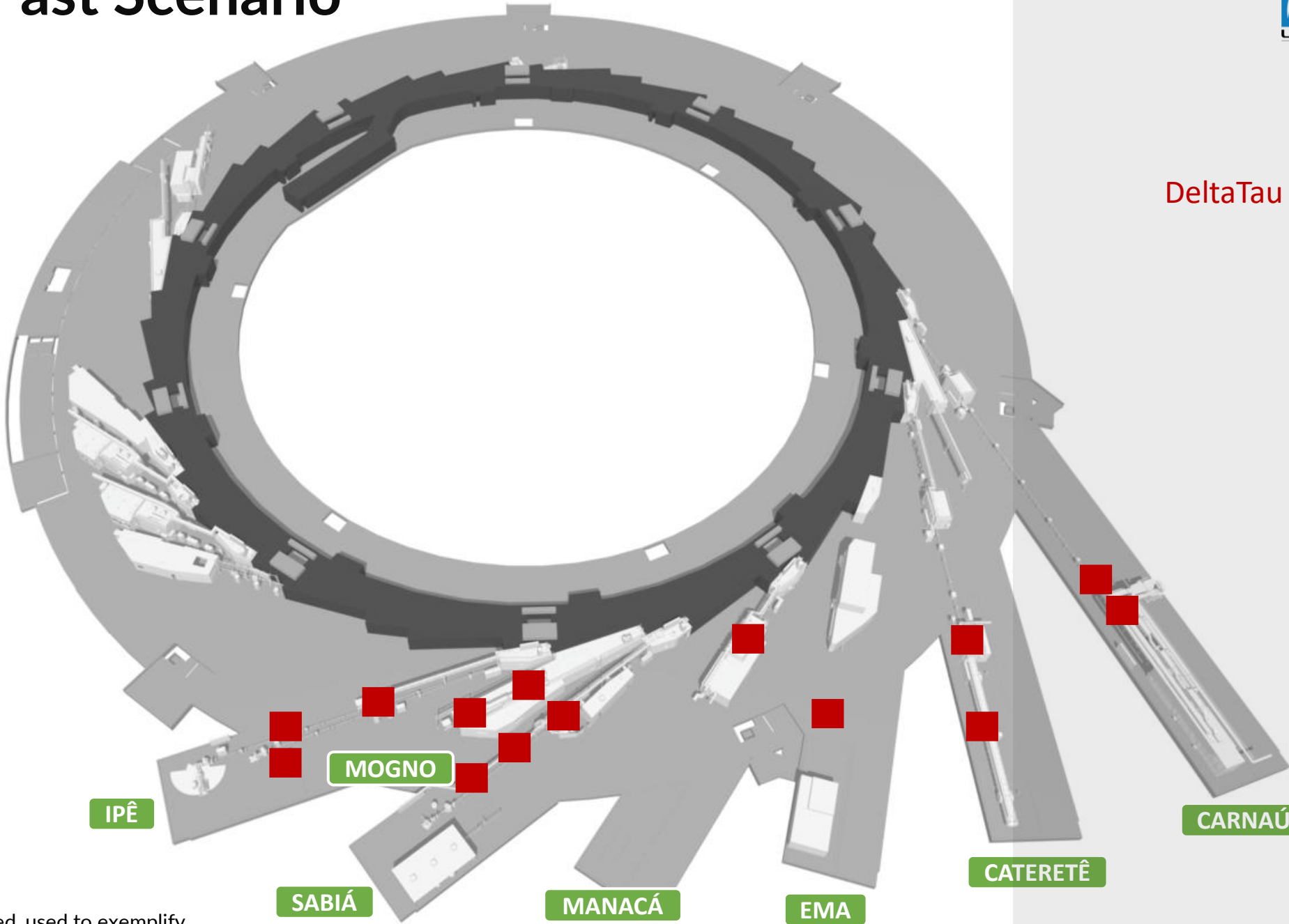
GBs Past Scenario



DeltaTau GB Project and code:

- s-cnb-gb01
- s-cnb-gb02
- s-cat-gb01
- s-cat-gb02
- s-ema-gb01
- s-mnc-gb01
- s-sab-gb01
- s-sab-gb02
- s-sab-gb03
- s-mgn-gb01
- s-mgn-gb02
- s-ipe-gb01
- s-ipe-gb02
- s-ipe-gb03

N

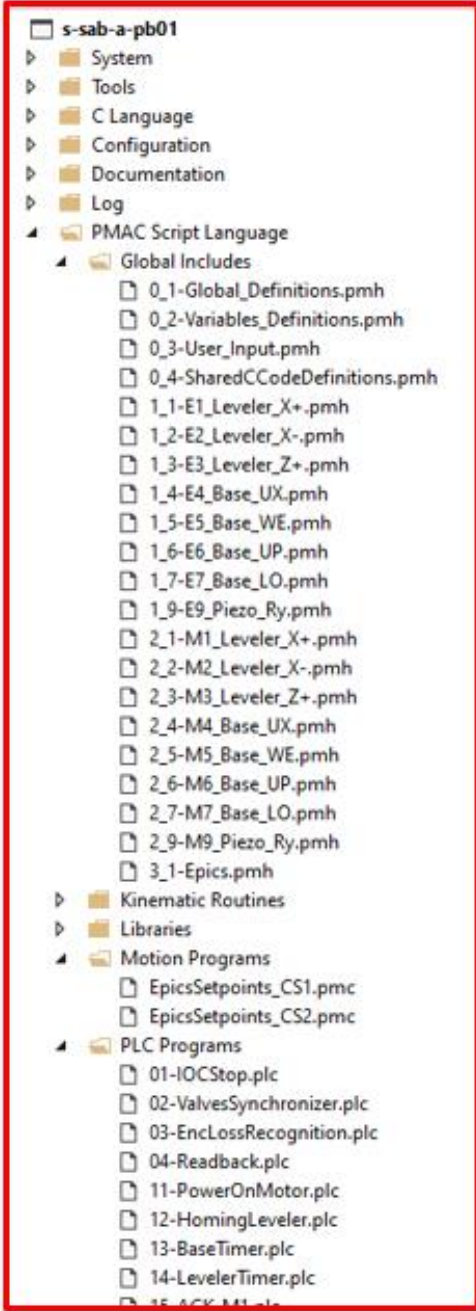
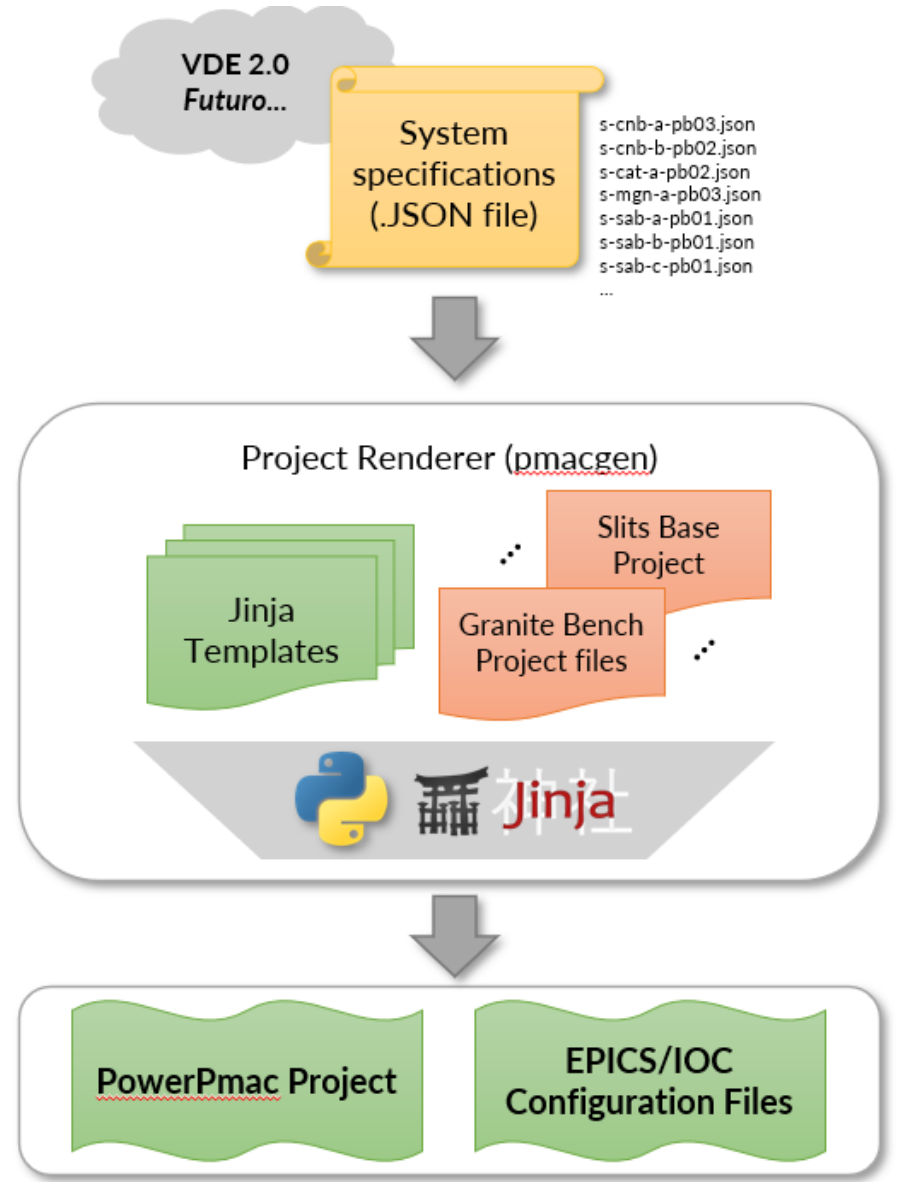


Not fully updated, used to exemplify

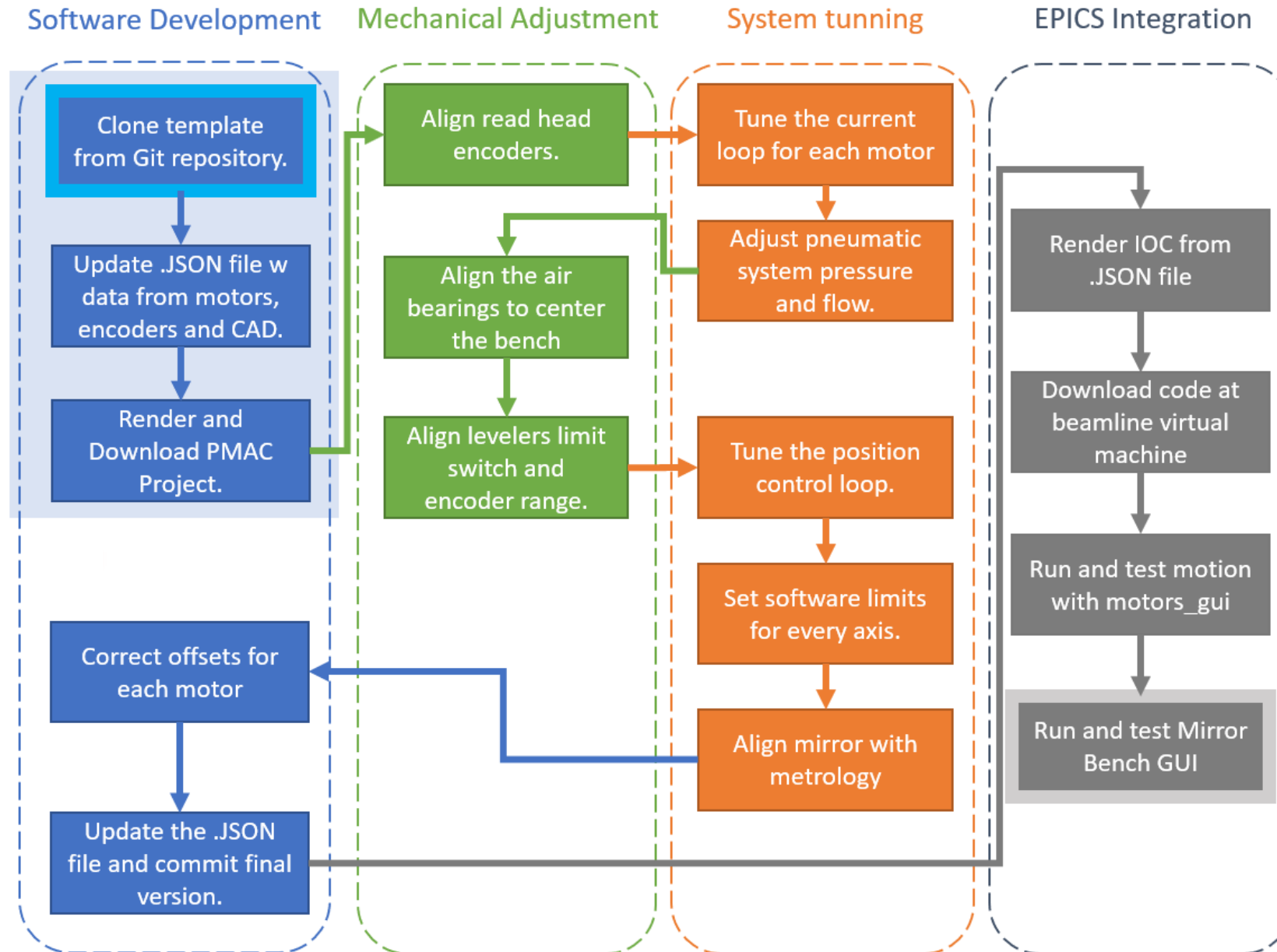
Power Pmac Project Generation



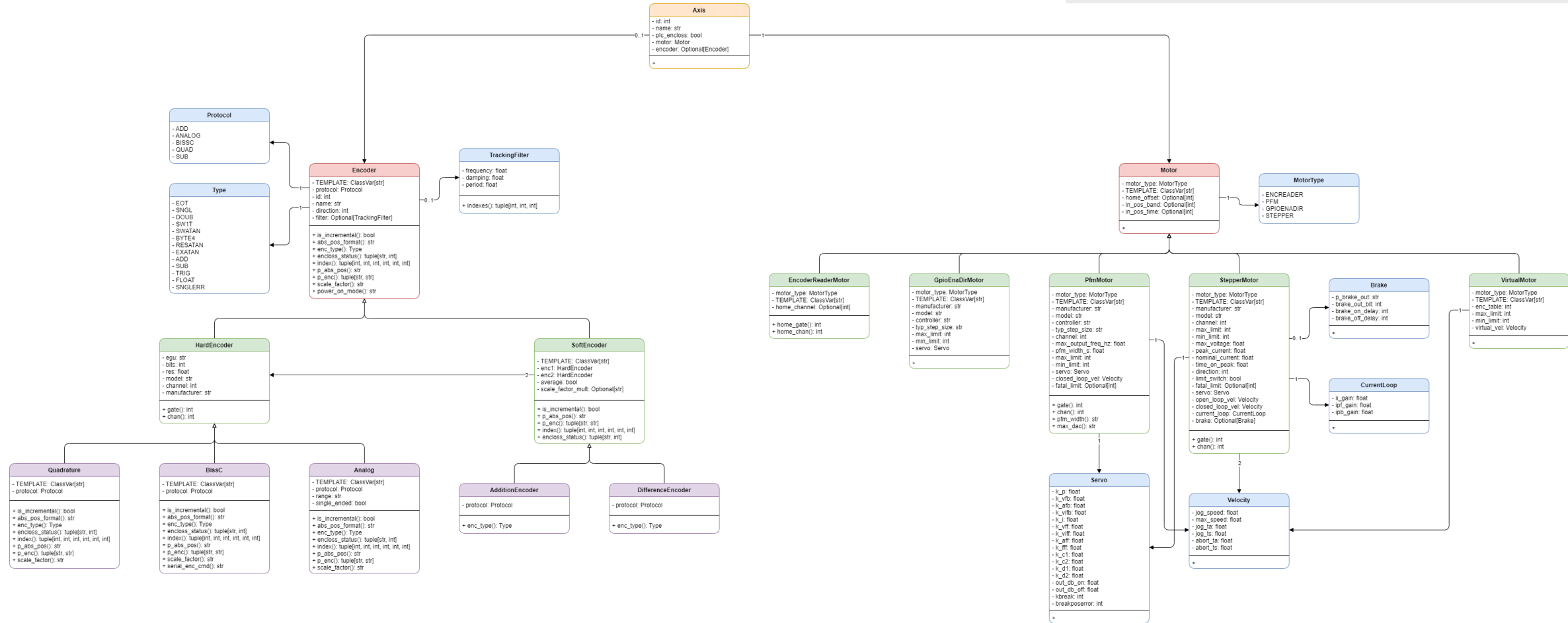
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Power Pmac Project Generation



Class Diagram of PMACGEN Library



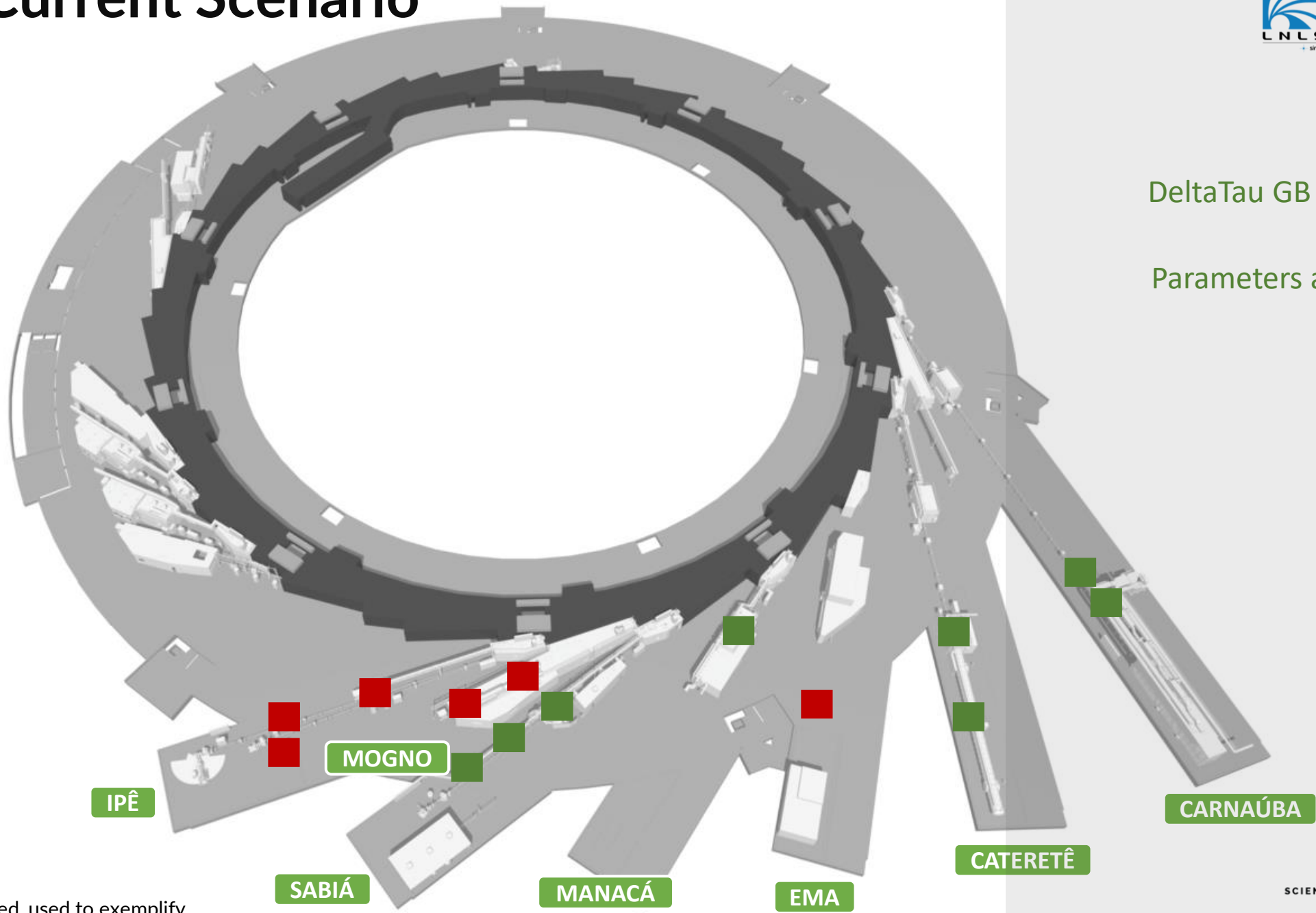
GBs Current Scenario



DeltaTau GB Project and code:
s-gbX

Parameters and deployed code

- s-cnb-gb01
- s-cnb-gb02
- s-cat-gb01
- s-cat-gb02
- s-mnc-gb01
- s-sab-gb01
- s-sab-gb02
- s-sab-gb03
- s-ipe-gb01
- s-ipe-gb02
- s-ipe-gb03



Not fully updated, used to exemplify

Summary

Advantages of rendering projects from data files:

- Maintain only one repository, single source of truth
- Increase standardization among mirror granite benches
- Reduce maintenance cost by speeding upgrade to future versions
- Concentrate the parameters of each system in one database



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THANK YOU

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SCIENCE TECHNOLOGY
AND INNOVATION

